

dissolution caused by fingering phenomena.

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Abstract

The next-generation multiphase-multicomponent reactive flow and transport code PFLOTRAN is

currently being developed under a SciDAC-2 project entitled: Modeling Multiscale-Multiphase-

Multicomponent Subsurface Reactive Flows using Advanced Computing. PFLOTRAN is a parallel mul-

tiphase flow and multicomponent reactive transport model written from the ground up employing PETSc

data structures and solvers for its parallel framework. The code employs domain decomposition for

parallelization and implements an efficient parallel I/O through HDF5. It is written in a highly modular,

object-oriented style in Fortran 90 and uses modern constructs such as derived types, pointers, and

linked lists. Recently, PFLOTRAN has been run on a one billion node real-world problem (Hanford 300

Area) as proof-of-concept for petascale computing. It ran successfully on 1024 cores on ORNL's Jaguar

Cray XT3 computer. The code has also demonstrated a relative parallel efficiency of 79% at 12,000

cores based on a strong-scaling study performed with a similar 500 million node problem executed on

3,000-12,000 cores. PFLOTRAN is currently being applied to investigate sequestration of CO_2 in vari-

ous geologic media including depleted oil reservoirs and saline aguifers as a possible solution to reduce

green house gas emissions. Dissolution of supercritical CO_2 in formation brines is considered an im-

portant storage mechanism to prevent possible leakage. Accurate prediction of the plume dissolution

rate and migration is essential. Analytical analysis and numerical experiments have demonstrated that

convective instability (Rayleigh instability) has a crucial effect on the dissolution behavior and subse-

quent mineralization reactions. Global stability analysis indicates that a certain grid resolution is needed

to capture the features of density-driven fingering phenomena. For 3-D field scale simulations, high

resolution leads to large numbers of grid nodes, unfeasible for a single workstation. In this study, we

investigate the effects of convective instability on geologic sequestration of CO_2 by taking advantage

of parallel computing using PFLOTRAN. The onset, development and long-term fate of a supercritica

CO₂ plume will be resolved with high-resolution numerical simulations to investigate the rate of plume



The Next-Generation Massively Parallel Reactive Flow and Transport Code PFLOTRAN: Application to CO₂ Storage in Saline Aquifers

al., 1996):

for the jth primary species, and

for the mth mineral.

where C_i^{α} denotes the solute concentration in phase α , C_i^{α} denotes the concentration of the *i*th secondary species, related to the concentration of primary species through the mass action equations

where the subscript (g) refers to the supercritical phase and (ag) to the aqueous phase. Other reactions not included above that may also significantly impact CO_2 sequestration are ion exchange and surface complexation reactions since these reactions could affect the concentrations of relevant cations such as Ca^{2+} and Mg^{2+}

1. Introduction

- Sequestration of CO₂ in subsurface geologic formations containing saline aquifers could provide permanent storage for a major greenhouse gas and thereby help to mitigate global climate change.
- Saline aquifers have an estimated world-wide storage capacity for CO₂ of 320-10,000 Gt CO₂ (Bachu, 2002)
- A typical scenario is injection into a relatively deep saline aquifer above the critical point where CO₂ exists as a supercritical fluid ($T_{\rm crit} = 31.04^{\circ}$ C, $p_{\rm crit} = 73.82$ bar).
- \checkmark As supercritical CO₂ is injected into the aquifer it becomes buoyant because of its lower density compared to the brine and begins to rise, possibly eventually reaching the ground surface (Pruess, 2006). A low permeability zone or caprock may trap the CO_2 so that it can gradually dissolve into the surrounding brine.
- \checkmark As the CO₂ dissolves into the brine, the brine becomes heavier and begins to sink resulting in density-driven convection which can lead to instabilities resulting in the formation of CO_2 concentrated brine fingers protruding downward.
- \square The areal extent of the plume can have an important effect on accidental release of CO₂ to the surface through abandoned bore holes and faults. The areal extent is controlled by competition between the rate of spreading of the plume and the rate at which it dissolves into the brine. Convective mixing can result in much more rapid dissipation of the supercritical CO₂ plume compared to diffusive processes alone.
- It is important to understand the properties of the aquifer which determine the size and onset of fingering during the convective mixing process.
- \checkmark Analyses of density instability of CO₂ in deep saline aquifers can be used to investigate the onset of convective mixing during CO₂ sequestration in isotropic and anisotropic porous media (Ennis-King and Paterson, 2003; Xu et al., 2006)

2. The Massively Parallel Reactive Flow and Transport Code PFLOTRAN

- Intersection of the system tions for a number of phases including H_2O , supercritical CO_2 , and black oil, and a gaseous phase. PFLOTRAN describes coupled thermal-hydrologic-chemical (THC) processes in variably saturated, nonisothermal, porous media in one (1D), two (2D), or three (3D) spatial dimensions
- In the multiphase partial differential equations solved by PFLOW for mass and energy conservation can be summarized as (Lichtner et al., 1996):

$$\frac{\partial}{\partial t} \left(\phi \sum_{\alpha} s_{\alpha} \rho_{\alpha} X_{i}^{\alpha} \right) + \boldsymbol{\nabla} \cdot \sum_{\alpha} \left[\boldsymbol{q}_{\alpha} \rho_{\alpha} X_{i}^{\alpha} - \phi s_{\alpha} D_{\alpha} \rho_{\alpha} \boldsymbol{\nabla} X_{i}^{\alpha} \right] = Q_{i}^{\alpha}, \quad (1a)$$

and

$$\frac{\partial}{\partial t} \left(\phi \sum_{\alpha} s_{\alpha} \rho_{\alpha} U_{\alpha} + (1 - \phi) \rho_{r} c_{r} T \right) + \boldsymbol{\nabla} \cdot \left[\boldsymbol{q}_{\alpha} \rho_{\alpha} H_{\alpha} - \kappa \boldsymbol{\nabla} T \right] = Q_{e}.$$
(1b)

In these equations, α designates a phase (e.g. H₂O, supercritical CO₂, g), species are designated by the subscript i (e.g. $w = H_2O$, $c = CO_2$), ϕ denotes porosity of the geologic formation, s_{α} denotes the saturation state of the phase; X_i^{α} denotes the mole fraction of species i; ρ_{α} , H_{α} , U_{α} refer to the molar density, enthalpy, and internal energy of each fluid phase, respectively; q_{α} denotes the Darcy flow rate defined by

$$\boldsymbol{q}_{\alpha} = -\frac{kk_{\alpha}}{\mu_{\alpha}}\boldsymbol{\nabla} (p_{\alpha} - W_{\alpha}\rho_{\alpha}g\boldsymbol{z}), \qquad (2)$$

where k refers to the water saturated permeability, k_{α} denotes the relative permeability, μ_{α} denotes the fluid viscosity, W_{α} denotes the formula weight, and g denotes the acceleration of gravity. The source/sink terms Q_i^{α} and Q_e , describe injection and extraction at wells. The density ρ_{α} of fluid phase α appearing in Eqns. (1a) and (1b) refers to the density of the fluid mixture. Use of ideal mixing for the system H_2O-CO_2 leads to a lower density of the mixture. In this work the correlation developed by Garcia (2001) is used which gives a greater mixture density in agreement with experiment. Finally, a Henry's law relation from Duan and Sun (2003) is used to compute the equilibrium concentration of CO_2 dissolved in H_2O of the form

$$X_i^{\beta} = K_{i,\beta\alpha} X_i^{\alpha}, \qquad ($$

with Henry constant $K_{i,\beta\alpha}$, with $i = CO_2$, $\alpha = CO_{2(sc)}$, and $\beta = H_2O$.

⊢ Timestep

ciency.

tions.

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Intermulticomponent reactive transport equations solved by PFLOTRAN have the form (Lichtner et al. 2010)

$$\frac{\partial}{\partial t} \left(\phi \sum_{\alpha} s_{\alpha} \Psi_{j}^{\alpha} \right) + \boldsymbol{\nabla} \cdot \sum_{\alpha} \boldsymbol{\Omega}_{j}^{\alpha} = -\sum_{m} \nu_{jm} I_{m}, \qquad ($$

$$= \overline{V}_m I_m,$$

Solutions: Ψ_i^{α} , Ω_i^{α} denote the total concentration and flux, defined by the expressions

$$_{j}^{\alpha} = \delta_{\alpha l}C_{j}^{\alpha} + \sum_{i} \nu_{ji}C_{i}^{\alpha}, \quad \boldsymbol{\Omega}_{j}^{\alpha} = (-\tau\phi s_{\alpha}D_{\alpha}\boldsymbol{\nabla} + \boldsymbol{q}_{\alpha})\Psi_{j}^{\alpha},$$
 (6)

$$C_i^{\alpha} = (\gamma_i^{\alpha})^{-1} K_i^{\alpha} \prod_j \left(\gamma_j^{\alpha} C_j^{\alpha}\right)^{\nu_{ji}^{\alpha}}, \tag{7}$$

where γ_i^{α} denotes the activity coefficient, and K_i^{α} denotes the equilibrium constant for the reaction. \blacksquare Partitioning CO₂ between H₂O and supercritical CO₂ is accomplished with the reaction

$$CO_{2(aq)} \rightleftharpoons CO_{2(g)},$$
 (8)

3. Parallel Implementation

PFLOTRAN is written from the ground up to run on massively parallel computer architectures (Hammond et al., 2005, 2007; Lu and Lichtner, 2007; Mills et al., 2007).

PFLOTRAN makes use of object-oriented features in Fortran 90 and is essentially platform independent, running on any machine that PETSc runs on. This includes laptop computers, workstations, and massively parallel high performance computing facilities. See flow diagram for PFLOTRAN shown in Figure 1. The realization-level-patch grid structure for implementing structured AMR and multilevel solvers is illustrated in Figure 2.

Parallelization is implemented through the PETSc parallel library developed at Argonne National Laboratory (Balay et al., 1997).

PETSc provides a user friendly set of routines for solving systems of nonlinear equations in parallel using domain decomposition [Figure 3(a)].

PETSc includes parallel solvers and preconditioners, parallel construction of the Jacobian matrix and residual function, and seamless message passing, which together provide a high parallel effi-

PETSc (latest version 2.3.3) has achieved a high level of maturity that allows rapid development with efficient parallel implementation for solving large systems of non-linear partial differential equa-

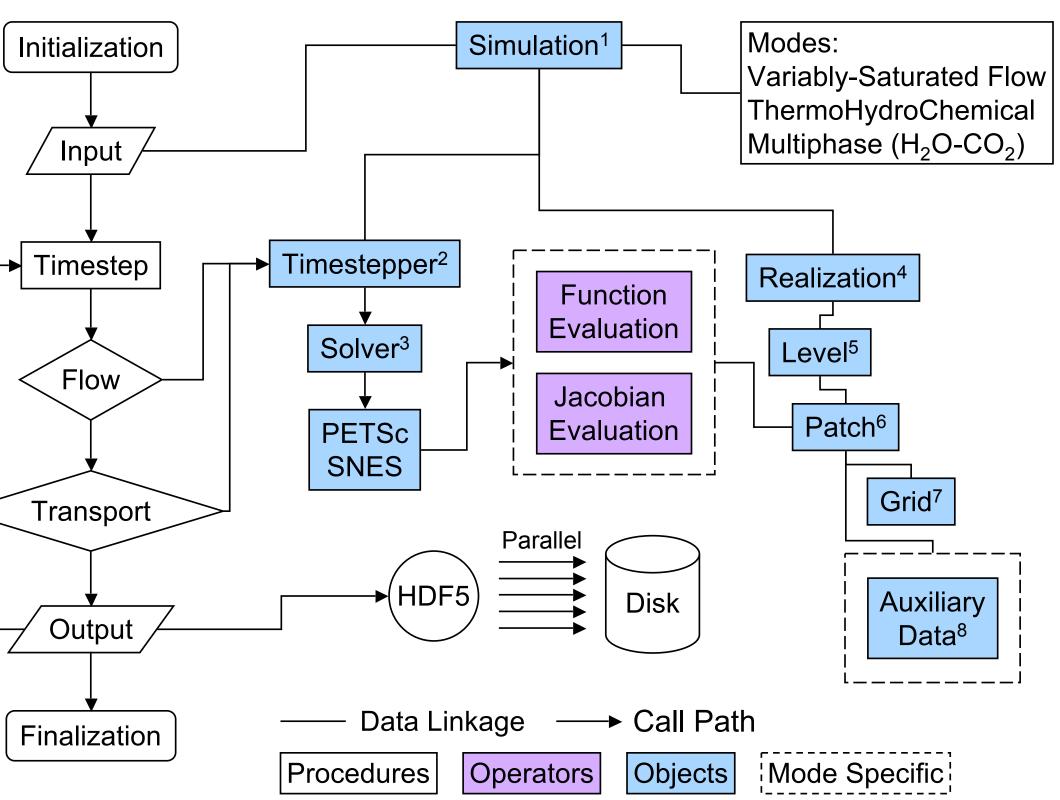


Figure 1: PFLOTRAN flow diagram illustrating use of procedures, operators, objects, and mode specific operators and objects.

Flow Chart Definitions

1. Simulation object: Highest level data structure providing all information for running a simulation 2. Timestepper object: Pointer to Newton-Krylov solver and tolerances associated with time stepping 3. Solver object: Pointer to nonlinear Newton and linear Krylov solvers (PETSc SNES/KSP/PC) along with associated convergence criteria

- tion of a simulation
- finement within a realization
- within a level
- 7. Grid object: Pointer to discretization within a patch
- 8. Auxiliary Data object: Pointer to field variables within a patch

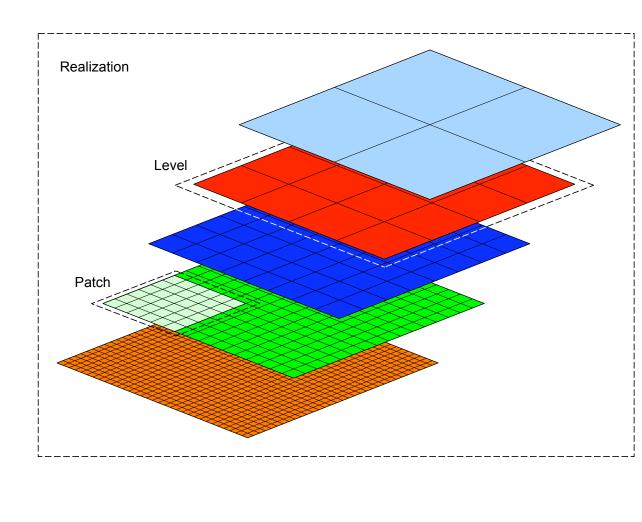


Figure 2: Realization-level-patch grid structure used in PFLO TRAN for implementing AMR and multilevel solvers.

Strong scaling results are shown in Figure 3(b) for modest sized problems running on MPP2 at PNNL/EMSL and Jaguar at ORNL (Mills et al., 2005). The benchmark problems were run on both the MPP2 cluster at PNNL/EMSL, a cluster of 1960 1.5 GHz Itanium 2 processors with Quadrics Qs-NetII interconnect, and Jaguar, the 5294 Opteron processor Cray XT3 at ORNL/NCCS. PFLOTRAN scales quite well on both machines, bottoming out at around 1024 processors on MPP2, and scaling exceptionally well on Jaguar, displaying linear speedup all the way up to 2048 processors, and still dis playing good speedup when going from there to 4096 processors. Transport (PTRAN) was run only on MPP2 and shows similar scaling to flow (PFLOW).

Flow of Control for PDE Solution

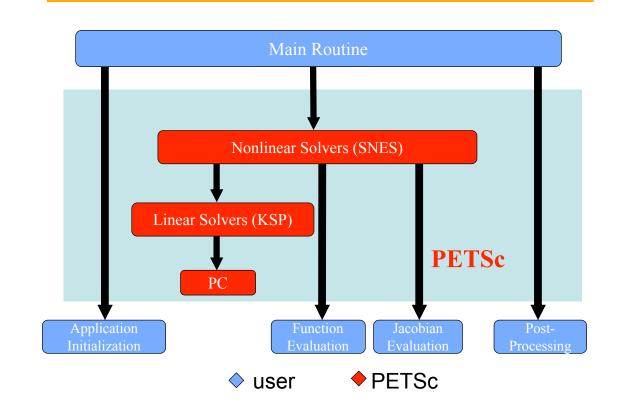


Figure 3: (a) PETSc provides message passing capabilities, solvers and preconditions for parallel computing (left). The user supplies the residual function and Jacobian. (b) Performance of PFLOTRAN (PFLOW refers to flow and PTRAN to reactive transport) (right) running a single phase thermo-hydrologic benchmark problem on a 256×64×256 grid with three and four degrees of freedom per node, respectively (approximately 12.6 and 16.8 million degrees of freedom total).

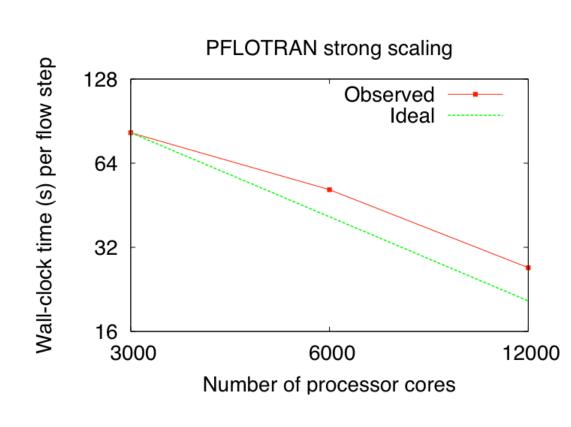


Figure 4: (a) Strong scaling speedup curve for 500 million node problem run on Jaguar.

Figure 4(a) shows the wall-clock time versus the number of processor cores for a 500 million node problem run on Jaguar at ORNL using dual-core processors. Scaling is reasonable and the slight reduction in performance is attributed to load imbalance due to the use of inactive nodes in the calculation Recently, PFLOTRAN has been run on a one billion node $(4096 \times 2048 \times 128 = 1,073,741,824 \text{ nodes})$. real-world problem (Hanford 300 Area) as proof-of-concept for petascale computing. Timing for a single step are presented in Figure 4(b).

4. Convective Mixing

4.1 PFLOTRAN Simulations

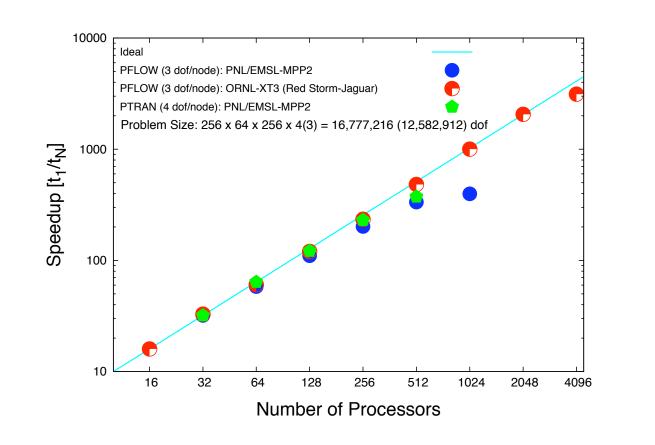
Two 3D simulations are presented involving a coarse and fine grid for a sandstone host rock containing calcite cement (Lu and Lichtner, 2007). In both simulations an isotropic permeability of 2×10^{-12} m²

4. Realization object: Pointer to all discretization and field variables associated with a single realiza

5. Level object: Pointer to discretization and field variables associated with a single level of grid re-

6. Patch object: Pointer to discretization and field variables associated with a subset of grid cells

- Key PFLOTRAN features/capabilities either implemented or currently being implemented (*)
- Object-oriented data structures
- PETSc solvers/preconditioners
- Modular linkage to physicochemical processes
- Collective parallel I/O through HDF5 AMR*
- Multicontinuum subgrid model*
- Multiphase flow
- Thermal transport
- Multicomponent transport
- Biogeochemistr



)ne-billic	on node per	formance	on Jagua
# procs	newton its	bcgs its	time(sec)
1024	16	1697	1143
2048	16	1626	697
4096	16	1720	325

Figure 4: (b) Jaguar performance for one billion node problem.

is used with a porosity of 15%. The nominal temperature and pressure is 50°C and 200 bars. The computational domain is 250 m thick and 7×7 km in lateral extent. CO₂ is injected at a depth of 50 m below the top of the domain. No flow boundary conditions are imposed at the top, bottom, front and back of the domain with constant pressure at the left and right sides. An injection rate of 1 Mt/y for 20 years was used in the simulations. This corresponds to roughly 75% of the CO₂ produced by a 1000 \pm MW gas-fired power plant in 20 years.

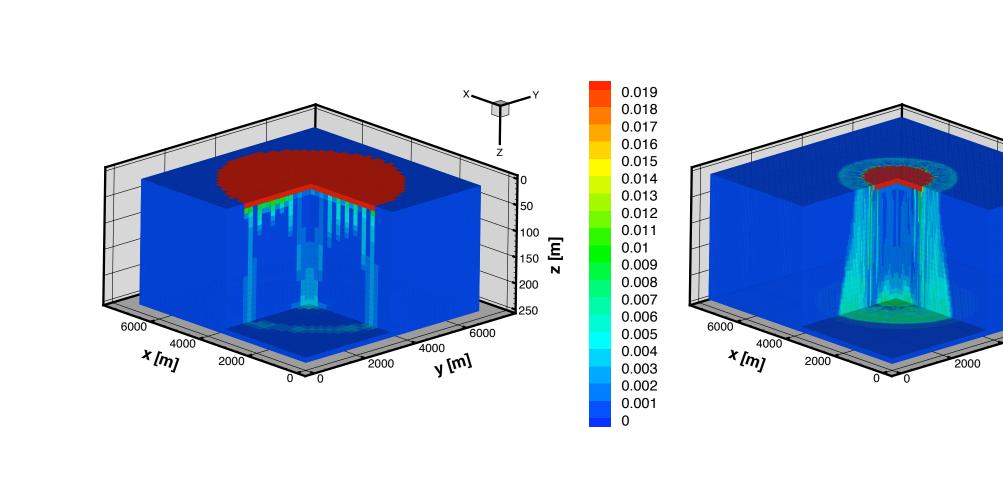
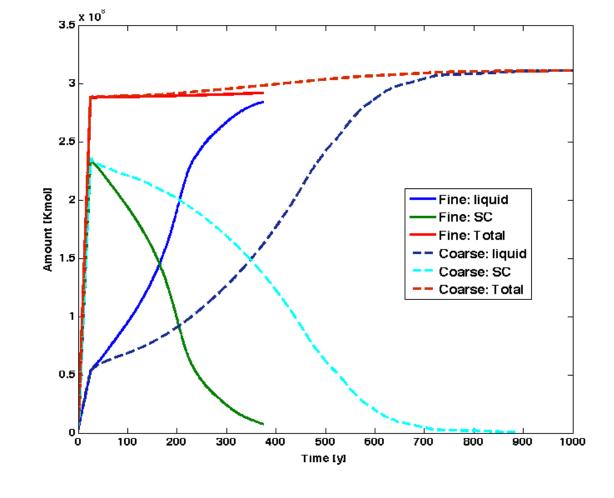


Figure 5: (a) Coarse grid.

Figure 5: (b) Fine grid.

Shown in Figure 5 is the dissolved CO_2 mole fraction corresponding to an elapsed time of 300 years calculated on a coarse-grid with $40 \times 40 \times 25$ nodes. The grid spacing is 175 m horizontally and 10 m vertically. In Figure 5 the grid is refined in the x and y directions by a factor of 4 with the same grid spacing in the z direction. In the find grid simulation 128 processors were used. For both simulations the finger width is equal to the horizontal grid spacing indicating that convergence is not obtained. Indeed, for the parameters used in the simulations according to stability analysis, the critical wavelength should be on the order of $\lambda_c = 0.05$ m and $\tau_c = 6.2 \times 10^{-4}$ y. This is much too small to resolve even with the fastest computers using a uniform grid.

In Figure 6(a) the total moles of CO_2 is plotted as a function of time for both coarse and fine grids showing the amount of CO₂ dissolved in the brine and as supercritical CO₂. The supercritical phase disappears at approximately 400 years for the fine grid compared to 800 years for the coarse grid. A slight increase in total CO₂ occurs due to the dissolution of calcite cement resulting from carbonic acid produced by injection of supercritical CO_2 .



Shown in Figures 7(a) and 7(b) are the pH and calcite volume fraction after an elapsed time of 1000 years. The pH is lower in the region containing elevated CO₂ concentrations. Very little reaction with calcite occurs within the formation except at the top where high CO_2 concentrations persist. The effect of temperature on the reaction instability is illustrated in Figures 8 and 9 where $T = 50^{\circ}$ C, 150°C and 250°C. At higher temperature the mixture density becomes less than the brine density and the dissolved CO₂ rises.

Figure 6: Supercritical, aqueous and total CO_2 plotted as a function of time for coarse and fine grids.

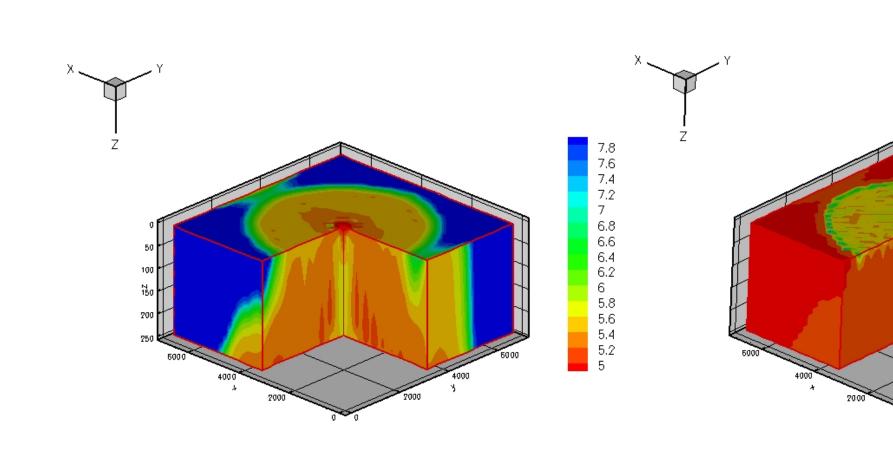
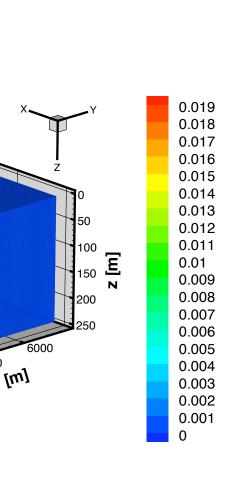
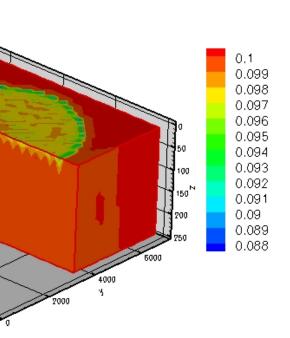


Figure 7: (a) pH after 1000 years.

Figure 7: (b) Calcite volume fraction after 1000 years.









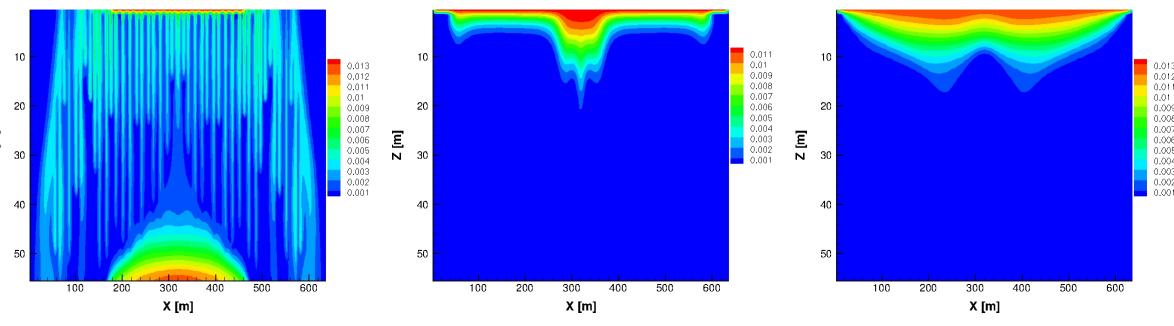


Figure 8: Calculated dissolved CO₂ profiles at different temperatures of 50°C, 162°C and 200°C from left to right for a 3m NaCl brine as the mixture density varies from greater, to equal, to less than the brine density.

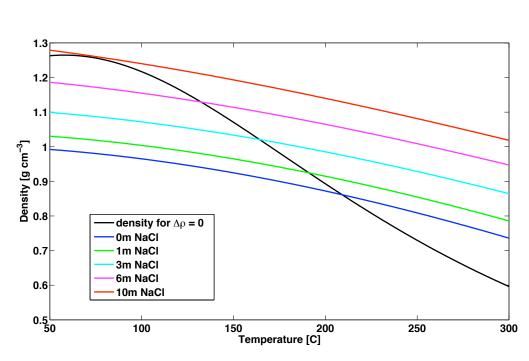


Figure 9: *Mixture density as a function of temperature based on the Garcia (2001) correlation based on* non-ideal mixing. The quantity $\Delta \rho$ denotes the difference in mixture and brine densities.

5. Conclusion

- PFLOTRAN's objected-oriented structure provides a flexible and modular framework for adding additional capabilities for scientific applications.
- PFLOTRAN was demonstrated to scale to one-billion nodes on 1024 processors, run on Jaguar at ORNL, as proof-of-concept for petascale computing.
- \checkmark The calculated rate of dissolution of CO₂ into the formation brine of a saline aguifer in which supercritical CO₂ is injected was found to be highly dependent on grid resolution because of density-driven instabilities resulting in fingering of the dissolved CO_2 .
- According to stability analysis, finger width can range over many orders of magnitude and for highly permeable regions may be too small to resolve even with massively parallel computing architectures.
- Numerical experiments utilizing massive parallel computing can provide the basis for formulating such upscaling relations.

Acknowledgments

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